

第7章习题答案

1. 检验以下集合对于所指的线性运算是否构成实数域上的线性空间?

(1) 2 阶对称矩阵的全体, 对于矩阵的加法和数量乘法;

解:

将 2 阶对称矩阵的全体记为 S_2 , 矩阵加法记为“+”, 矩阵的数量乘法记为“·”.

对加法封闭: 对任意 $A, B \in S_2$, 有 $(A+B)^T = A^T + B^T = A + B$, 所以 $A + B \in S_2$;

对数乘封闭: 对任意 $k \in \mathbf{R}$, $A \in S_2$, 有 $(k \cdot A)^T = k \cdot A^T = k \cdot A$, 所以 $k \cdot A \in S_2$;

对任意 $A, B, C \in S_2$, $k, m \in \mathbf{R}$, 下面 8 条运算规律成立:

$$A + B = B + A;$$

$$(A + B) + C = A + (B + C);$$

S_2 中的元素 $\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$ 满足 $A + \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} = A$ ($\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$ 称为零元素);

$A + (-A) = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$ ($-A$ 称为 A 的负元素);

$$1 \cdot A = A;$$

$$k \cdot (m \cdot A) = (km) \cdot A;$$

$$(k+m) \cdot A = k \cdot A + m \cdot A;$$

$$k \cdot (A+B) = k \cdot A + k \cdot B.$$

所以 2 阶对称矩阵的全体, 对于矩阵的加法和数量乘法构成实数域上的线性空间.

(2) 平面上全体向量, 对于通常的加法和如下定义的数量乘法:

$$k \cdot \alpha = \alpha;$$

解:

对于 $\alpha = (1, 1)$, $k = 1$, $m = 1$, 我们有:

$$(k+m) \cdot \alpha = (1, 1) \neq (1, 1) + (1, 1) = k \cdot \alpha + m \cdot \alpha$$

所以平面上全体向量, 对于通常的加法和如下定义的数量乘法:

$$k \cdot \alpha = \alpha$$

不构成实数域上的线性空间.

(3) 全体实数对 $\{(a, b) \mid a, b \in \mathbf{R}\}$, 对于如下定义的加法 \oplus 和数量乘法 \otimes :

$$(a_1, b_1) \oplus (a_2, b_2) = (a_1 + a_2, b_1 + b_2 + a_1 a_2)$$

$$k \oplus (a_1, b_1) = \left(ka_1, kb_1 + \frac{k(k-1)}{2}a_1^2\right).$$

解:

将全体实数对 $\{(a, b) \mid a, b \in \mathbf{R}\}$ 记为 \mathbf{R}_2 .

对加法封闭: 对任意 $(a_1, b_1), (a_2, b_2) \in \mathbf{R}_2$, 有:

$$(a_1, b_1) \oplus (a_2, b_2) = (a_1 + a_2, b_1 + b_2 + a_1 a_2) \in \mathbf{R}_2$$

对数乘封闭: 对任意 $k \in \mathbf{R}$, $(a, b) \in \mathbf{R}_2$, 有:

$$k \otimes (a, b) = (ka, kb + \frac{k(k-1)}{2}a^2) \in \mathbf{R}_2$$

对任意 $(a_1, b_1), (a_2, b_2), (a_3, b_3) \in \mathbf{R}_2, k, m \in \mathbf{R}$, 下面 8 条运算规律成立:

$$(a_1, b_1) \oplus (a_2, b_2) = (a_1 + a_2, b_1 + b_2 + a_1 a_2) = (a_2 + a_1, b_2 + b_1 + a_2 a_1) = (a_2, b_2) \oplus (a_1, b_1)$$

$$((a_1, b_1) \oplus (a_2, b_2)) \oplus (a_3, b_3) = (a_1 + a_2, b_1 + b_2 + a_1 a_2) \oplus (a_3, b_3)$$

$$= (a_1 + a_2 + a_3, b_1 + b_2 + a_1 a_2 + b_3 + (a_1 + a_2) a_3)$$

$$= (a_1 + a_2 + a_3, b_1 + b_2 + b_3 + a_2 a_3 + a_1 (a_2 + a_3))$$

$$= (a_1, b_1) \oplus (a_2 + a_3, b_2 + b_3 + a_2 a_3)$$

$$= (a_1, b_1) \oplus ((a_2, b_2) \oplus (a_3, b_3))$$

$$\mathbf{R}_2 \text{ 中的元素 } (0, 0) \text{ 满足 } (a_1, b_1) \oplus (0, 0) = (a_1 + 0, b_1 + 0 + a_1 \cdot 0) = (a_1, b_1),$$

$((0, 0)$ 称为零元素);

$$(a_1, b_1) \oplus (-a_1, -b_1 + a_1^2) = (a_1 + (-a_1), b_1 + (-b_1 + a_1^2) + a_1(-a_1)) = (0, 0),$$

$((-a_1, -b_1 + a_1^2)$ 称为 (a_1, b_1) 的负元素);

$$1 \otimes (a_1, b_1) = \left(1a_1, 1b_1 + \frac{1(1-1)}{2}a_1^2\right) = (a_1, b_1);$$

$$k \otimes (m \otimes (a_1, b_1)) = k \otimes \left(ma_1, mb_1 + \frac{m(m-1)}{2}a_1^2\right)$$

$$= \left(kma_1, k\left(mb_1 + \frac{m(m-1)}{2}a_1^2\right) + \frac{k(k-1)}{2}(ma_1)^2\right);$$

$$= \left(kma_1, kmb_1 + \frac{km(km-1)}{2}a_1^2\right) = (km) \otimes (a_1, b_1)$$

$$(k+m) \otimes (a_1, b_1) = \left((k+m)a_1, (k+m)b_1 + \frac{(k+m)(k+m-1)}{2}a_1^2\right)$$

$$= \left(ka_1 + ma_1, kb_1 + mb_1 + \frac{k^2 + 2km + m^2 - k - m}{2}a_1^2\right)$$

$$= \left(ka_1 + ma_1, kb_1 + \frac{k(k-1)}{2}a_1^2 + mb_1 + \frac{m(m-1)}{2}a_1^2 + ka_1 ma_1\right)$$

$$= \left(ka_1, kb_1 + \frac{k(k-1)}{2}a_1^2\right) \oplus \left(ma_1, mb_1 + \frac{m(m-1)}{2}a_1^2\right) = k \otimes (a_1, b_1) \oplus m \otimes (a_1, b_1)$$

$$k \otimes ((a_1, b_1) \oplus (a_2, b_2))$$

$$= k \otimes (a_1 + a_2, b_1 + b_2 + a_1 a_2)$$

$$= \left(k(a_1 + a_2), k(b_1 + b_2 + a_1 a_2) + \frac{k(k-1)}{2}(a_1 + a_2)^2\right)$$

$$= \left(ka_1 + ka_2, kb_1 + kb_2 + \frac{k(k-1)}{2}a_1^2 + \frac{k(k-1)}{2}a_2^2 + k^2 a_1 a_2\right)$$

$$= \left(ka_1 + ka_2, kb_1 + \frac{k(k-1)}{2}a_1^2 + kb_2 + \frac{k(k-1)}{2}a_2^2 + ka_1 ka_2\right)$$

$$= \left(ka_1, kb_1 + \frac{k(k-1)}{2}a_1^2\right) \oplus \left(ka_2, kb_2 + \frac{k(k-1)}{2}a_2^2\right)$$

$$= k \otimes (a_1, b_1) \oplus k \otimes (a_2, b_2)$$

所以全体实数对 $\{(a, b) | a, b \in \mathbf{R}\}$, 对于如下定义的加法 \oplus 和数量乘法 \otimes :

$$(a_1, b_1) \oplus (a_2, b_2) = (a_1 + a_2, b_1 + b_2 + a_1 a_2)$$

$$k \otimes (a_1, b_1) = \left(ka_1, kb_1 + \frac{k(k-1)}{2}a_1^2\right)$$

构成实数域上的线性空间.

2. 试判定下列各子集哪些为线性空间 \mathbf{R}^n 的子空间?

$$(1) W_1 = \{\mathbf{x} = (x_1, x_2, \dots, x_n)^T \in \mathbf{R}^n | x_1 + x_2 + \dots + x_n = 0\};$$

$$(2) W_2 = \{\mathbf{x} = (x_1, x_2, \dots, x_n)^T \in \mathbf{R}^n | x_1 x_2 \cdots x_n = 0\};$$

解:

(1) 任取 $\alpha = (x_1, x_2, \dots, x_n)^T, \beta = (y_1, y_2, \dots, y_n)^T \in W_1, k \in \mathbf{R}$, 有:

$$\alpha + \beta = (x_1 + y_1, x_2 + y_2, \dots, x_n + y_n)$$

满足

$$(x_1 + y_1) + (x_2 + y_2) + \dots + (x_n + y_n) = (x_1 + x_2 + \dots + x_n) + (y_1 + y_2 + \dots + y_n) = 0 + 0 = 0$$

所以有 $\alpha + \beta \in W_1$;

$$k\alpha = (kx_1, kx_2, \dots, kx_n) \text{ 满足: } kx_1 + kx_2 + \dots + kx_n = k(x_1 + x_2 + \dots + x_n) = k \cdot 0 = 0$$

所以有 $k\alpha \in W_1$;

由教材 P142 定理 7.2, W_1 为线性空间 \mathbf{R}^n 的子空间;

(2) 取 $\alpha = (\underbrace{1, 1, \dots, 1}_{n-1 \uparrow 1}, 0)^T, \beta = (\underbrace{0, 0, \dots, 0}_{n-1 \uparrow 0}, 1)^T$, 则 $\alpha, \beta \in W_2$, 但 $\alpha + \beta =$

$(\underbrace{1, 1, \dots, 1}_{n \uparrow 1})^T \notin W_2$, 由教材 P142 定理 7.2, W_2 不为线性空间 \mathbf{R}^n 的子空间.

3. 设 U 是线性空间 V 的一个子空间, 试证: 若 U 与 V 的维数相等, 则 $U = V$.

证明:

反证法. 如果 $U \neq V$, 则存在向量 $\alpha \in V, \alpha \notin U$.

设 U 与 V 的维数为 n . 取 U 的一组基: $\alpha_1, \alpha_2, \dots, \alpha_n$, 因为 U 是线性空间 V 的一个子空间, 所以 $\alpha_1, \alpha_2, \dots, \alpha_n$ 也是 V 中一组线性无关的向量.

由于 V 的维数为 n , 所以 V 作为向量组, 其秩为 n , $\alpha_1, \alpha_2, \dots, \alpha_n$ 是 V 的一个极大线性无关组. 由 $\alpha \in V$, 存在 k_1, k_2, \dots, k_n , 使得 $\alpha = k_1\alpha_1 + k_2\alpha_2 + \dots + k_n\alpha_n \in U$, 这与假设矛盾. 所以 $U = V$.

4. 设 $\alpha_1, \alpha_2, \dots, \alpha_r$ 是 n 维线性空间 V_n 的线性无关向量组, 证明 V_n 中存在向量 $\alpha_{r+1}, \dots, \alpha_n$, 使 $\alpha_1, \alpha_2, \dots, \alpha_r, \alpha_{r+1}, \dots, \alpha_n$ 成为 V_n 的一组基(对 $n-r$ 用数学归纳法).

证明:

因为 $\alpha_1, \alpha_2, \dots, \alpha_r$ 是 n 维线性空间 V_n 的线性无关向量组, 由 $r < n$ 可知, 存在 $\alpha_{r+1} \in V_n$ 无法由 $\alpha_1, \alpha_2, \dots, \alpha_r$ 线性表出(否则 V_n 可由 $\alpha_1, \alpha_2, \dots, \alpha_r$ 线性表出, 则 V_n 的维数为 $r < n$, 与题设矛盾), 于是 $\alpha_1, \alpha_2, \dots, \alpha_r, \alpha_{r+1}$ 仍然是 n 维线性空间 V_n 的线性无关向量组.

反复这样的添加向量 $\alpha_{r+2}, \dots, \alpha_n$, 最终得到 $\alpha_1, \alpha_2, \dots, \alpha_r, \alpha_{r+1}, \dots, \alpha_n$ 是 n 维线性空间 V_n 的线性无关向量组. 因为 n 维线性空间 V_n 作为向量组的秩为 n , 其中任意 n 个线性无关向量构成它的一个极大线性无关组, 也就是它的基, 所以 $\alpha_1, \alpha_2, \dots, \alpha_r, \alpha_{r+1}, \dots, \alpha_n$ 成为 V_n 的一组基.

5. 求 \mathbf{R}^3 中向量 $\alpha = (3, 7, 1)^T$ 在基 $\alpha_1 = (1, 3, 5)^T$, $\alpha_2 = (6, 3, 2)^T$, $\alpha_3 = (3, 1, 0)^T$ 下的坐标.

解:

设 $\alpha = x_1\alpha_1 + x_2\alpha_2 + x_3\alpha_3 = (\alpha_1, \alpha_2, \alpha_3) \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$, 则有:

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = (\alpha_1, \alpha_2, \alpha_3)^{-1}\alpha = \begin{pmatrix} 1 & 6 & 3 \\ 3 & 3 & 1 \\ 5 & 2 & 0 \end{pmatrix}^{-1} \begin{pmatrix} 3 \\ 7 \\ 1 \end{pmatrix}$$

因为:

$$\begin{aligned} & \begin{pmatrix} 1 & 6 & 3 & 1 & 0 & 0 \\ 3 & 3 & 1 & 0 & 1 & 0 \\ 5 & 2 & 0 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{-3r_1+r_2} \begin{pmatrix} 1 & 6 & 3 & 1 & 0 & 0 \\ 0 & -15 & -8 & -3 & 1 & 0 \\ 0 & -28 & -15 & -5 & 0 & 1 \end{pmatrix} \\ & \xrightarrow{-15r_3} \begin{pmatrix} 1 & 6 & 3 & 1 & 0 & 0 \\ 0 & -15 & -8 & -3 & 1 & 0 \\ 0 & 420 & 225 & 75 & 0 & -15 \end{pmatrix} \xrightarrow{28r_2+r_3} \begin{pmatrix} 1 & 6 & 3 & 1 & 0 & 0 \\ 0 & -15 & -8 & -3 & 1 & 0 \\ 0 & 0 & 1 & -9 & 28 & -15 \end{pmatrix} \\ & \xrightarrow{-3r_3+r_1} \begin{pmatrix} 1 & 6 & 0 & 28 & -84 & 45 \\ 0 & -15 & 0 & -75 & 225 & -120 \\ 0 & 0 & 1 & -9 & 28 & -15 \end{pmatrix} \xrightarrow{-\frac{1}{15}r_2} \begin{pmatrix} 1 & 0 & 0 & -2 & 6 & -3 \\ 0 & 1 & 0 & 5 & -15 & 8 \\ 0 & 0 & 1 & -9 & 28 & -15 \end{pmatrix} \\ & \text{所以有 } \begin{pmatrix} 1 & 6 & 3 \\ 3 & 3 & 1 \\ 5 & 2 & 0 \end{pmatrix}^{-1} = \begin{pmatrix} -2 & 6 & -3 \\ 5 & -15 & 8 \\ -9 & 28 & -15 \end{pmatrix}. \end{aligned}$$

$\alpha = (3, 7, 1)^T$ 在基 $\alpha_1 = (1, 3, 5)^T$, $\alpha_2 = (6, 3, 2)^T$, $\alpha_3 = (3, 1, 0)^T$ 下的坐标为:

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 & 6 & 3 \\ 3 & 3 & 1 \\ 5 & 2 & 0 \end{pmatrix}^{-1} \begin{pmatrix} 3 \\ 7 \\ 1 \end{pmatrix} = \begin{pmatrix} -2 & 6 & -3 \\ 5 & -15 & 8 \\ -9 & 28 & -15 \end{pmatrix} \begin{pmatrix} 3 \\ 7 \\ 1 \end{pmatrix} = \begin{pmatrix} 33 \\ -82 \\ 154 \end{pmatrix}$$

6. 在 \mathbf{R}^3 中, 取两个基:

$\alpha_1 = (1, 2, 1)$, $\alpha_2 = (2, 3, 3)$, $\alpha_3 = (3, 7, 1)$;

$\beta_1 = (3, 1, 4)$, $\beta_2 = (5, 2, 1)$, $\beta_3 = (1, 1, -6)$.

试求 α_1 , α_2 , α_3 到 β_1 , β_2 , β_3 的过渡矩阵与坐标变换公式.

解:

设 α_1 , α_2 , α_3 到 β_1 , β_2 , β_3 的过渡矩阵为 C , 则有:

$$\begin{pmatrix} \beta_1 \\ \beta_2 \\ \beta_3 \end{pmatrix} = C \begin{pmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{pmatrix}, C = \begin{pmatrix} \beta_1 \\ \beta_2 \\ \beta_3 \end{pmatrix} \begin{pmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{pmatrix}^{-1} = \begin{pmatrix} 3 & 1 & 4 \\ 5 & 2 & 1 \\ 1 & 1 & -6 \end{pmatrix} \begin{pmatrix} 1 & 2 & 1 \\ 2 & 3 & 3 \\ 3 & 7 & 1 \end{pmatrix}^{-1}$$

初等变换法求逆矩阵:

$$\begin{pmatrix} 1 & 2 & 1 & 1 & 0 & 0 \\ 2 & 3 & 3 & 0 & 1 & 0 \\ 3 & 7 & 1 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{-2r_1+r_2} \begin{pmatrix} 1 & 2 & 1 & 1 & 0 & 0 \\ 0 & -1 & 1 & -2 & 1 & 0 \\ 3 & 7 & 1 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{-3r_1+r_3} \begin{pmatrix} 1 & 2 & 1 & 1 & 0 & 0 \\ 0 & -1 & 1 & -2 & 1 & 0 \\ 0 & 1 & -2 & -3 & 0 & 1 \end{pmatrix}$$

$$\xrightarrow{r_2+r_3} \begin{pmatrix} 1 & 2 & 1 & 1 & 0 & 0 \\ 0 & -1 & 1 & -2 & 1 & 0 \\ 0 & 0 & -1 & -5 & 1 & 1 \end{pmatrix} \xrightarrow{r_3+r_1} \begin{pmatrix} 1 & 2 & 0 & -4 & 1 & 1 \\ 0 & -1 & 0 & -7 & 2 & 1 \\ 0 & 0 & -1 & -5 & 1 & 1 \end{pmatrix}$$

$$\xrightarrow{2r_2+r_3} \begin{pmatrix} 1 & 0 & 0 & -18 & 5 & 3 \\ 0 & -1 & 0 & -7 & 2 & 1 \\ 0 & 0 & -1 & -5 & 1 & 1 \end{pmatrix} \xrightarrow{-r_2} \begin{pmatrix} 1 & 0 & 0 & -18 & 5 & 3 \\ 0 & 1 & 0 & 7 & -2 & -1 \\ 0 & 0 & 1 & 5 & -1 & -1 \end{pmatrix}$$

所以有：

$$\begin{pmatrix} 1 & 2 & 1 \\ 2 & 3 & 3 \\ 3 & 7 & 1 \end{pmatrix}^{-1} = \begin{pmatrix} -18 & 5 & 3 \\ 7 & -2 & -1 \\ 5 & -1 & -1 \end{pmatrix}, C = \begin{pmatrix} 3 & 1 & 4 \\ 5 & 2 & 1 \\ 1 & 1 & -6 \end{pmatrix} \begin{pmatrix} -18 & 5 & 3 \\ 7 & -2 & -1 \\ 5 & -1 & -1 \end{pmatrix} = \begin{pmatrix} -27 & 9 & 4 \\ -71 & 20 & 12 \\ -41 & 9 & 8 \end{pmatrix}$$

设 \mathbf{R}^3 中向量 α 在 $\alpha_1, \alpha_2, \alpha_3$ 下的坐标为 (x_1, x_2, x_3) , 在 $\beta_1, \beta_2, \beta_3$ 下的坐标为 $(x'_1,$

$$(x'_2, x'_3)$$
, 则由 $(x_1, x_2, x_3) \begin{pmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{pmatrix} = \alpha = (x'_1, x'_2, x'_3) \begin{pmatrix} \beta_1 \\ \beta_2 \\ \beta_3 \end{pmatrix}$, 得初等变换公式:

$$(x_1, x_2, x_3) = (x'_1, x'_2, x'_3) \begin{pmatrix} \beta_1 \\ \beta_2 \\ \beta_3 \end{pmatrix} \begin{pmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{pmatrix}^{-1} = (x'_1, x'_2, x'_3) C = (x'_1, x'_2, x'_3) \begin{pmatrix} -27 & 9 & 4 \\ -71 & 20 & 12 \\ -41 & 9 & 8 \end{pmatrix}$$

7. 在 \mathbf{R}^4 中求基

$$\alpha_1 = (1, 0, 0, 0)^T, \alpha_2 = (0, 1, 0, 0)^T, \alpha_3 = (0, 0, 1, 0)^T, \alpha_4 = (0, 0, 0, 1)^T$$

到基

$$\beta_1 = (2, 1, -1, 1)^T, \beta_2 = (0, 3, 1, 0)^T, \beta_3 = (5, 3, 2, 1)^T, \beta_4 = (6, 6, 1, 3)^T$$

的过渡矩阵, 确定向量 $\xi = (x_1, x_2, x_3, x_4)^T$ 在后一个基下的坐标, 并求一非零向量, 使它在两组基下有相同的坐标.

解:

设 $\alpha_1, \alpha_2, \alpha_3, \alpha_4$ 到 $\beta_1, \beta_2, \beta_3, \beta_4$ 的过渡矩阵为 C , 则有:

$$(\alpha_1, \alpha_2, \alpha_3, \alpha_4) = (\beta_1, \beta_2, \beta_3, \beta_4) C,$$

$$C = (\beta_1, \beta_2, \beta_3, \beta_4)^{-1} (\alpha_1, \alpha_2, \alpha_3, \alpha_4) = \begin{pmatrix} 2 & 0 & 5 & 6 \\ 1 & 3 & 3 & 6 \\ -1 & 1 & 2 & 1 \\ 1 & 0 & 1 & 3 \end{pmatrix}^{-1} E = \begin{pmatrix} 2 & 0 & 5 & 6 \\ 1 & 3 & 3 & 6 \\ -1 & 1 & 2 & 1 \\ 1 & 0 & 1 & 3 \end{pmatrix}^{-1}$$

因为:

$$\begin{pmatrix} 2 & 0 & 5 & 6 & 1 & 0 & 0 & 0 \\ 1 & 3 & 3 & 6 & 0 & 1 & 0 & 0 \\ -1 & 1 & 2 & 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 3 & 0 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{-2r_4+r_1} \begin{pmatrix} 0 & 0 & 3 & 0 & 1 & 0 & 0 & -2 \\ 0 & 3 & 2 & 3 & 0 & 1 & 0 & -1 \\ 0 & 1 & 3 & 4 & 0 & 0 & 1 & 1 \\ 1 & 0 & 1 & 3 & 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\xrightarrow{-3r_3+r_2} \begin{pmatrix} 0 & 0 & 3 & 0 & 1 & 0 & 0 & -2 \\ 0 & 0 & -21 & -27 & 0 & 3 & -9 & -12 \\ 0 & 1 & 3 & 4 & 0 & 0 & 1 & 1 \\ 3 & 0 & 3 & 9 & 0 & 0 & 0 & 3 \end{pmatrix}$$

$$\xrightarrow{3r_4} \begin{pmatrix} 0 & 0 & 3 & 0 & 1 & 0 & 0 & -2 \\ 0 & 0 & -21 & -27 & 0 & 3 & -9 & -12 \\ 0 & 1 & 3 & 4 & 0 & 0 & 1 & 1 \\ 3 & 0 & 3 & 9 & 0 & 0 & 0 & 3 \end{pmatrix}$$

$$\begin{array}{l}
\begin{array}{c}
7r_1+r_2 \\
-r_1+r_3 \\
-r_1+r_4
\end{array} \rightarrow \left(\begin{array}{ccccccc} 0 & 0 & 3 & 0 & 1 & 0 & 0 & -2 \\ 0 & 0 & 0 & -27 & 7 & 3 & -9 & -26 \\ 0 & 1 & 0 & 4 & -1 & 0 & 1 & 3 \\ 3 & 0 & 0 & 9 & -1 & 0 & 0 & 5 \end{array} \right) \\
\begin{array}{c}
9r_1 \\
-r_2 \\
27r_3 \\
9r_4
\end{array} \rightarrow \left(\begin{array}{ccccccc} 0 & 0 & 27 & 0 & 9 & 0 & 0 & -18 \\ 0 & 0 & 0 & 27 & -7 & -3 & 9 & 26 \\ 0 & 27 & 0 & 108 & -27 & 0 & 27 & 81 \\ 27 & 0 & 0 & 81 & -9 & 0 & 0 & 45 \end{array} \right) \\
\begin{array}{c}
-4r_2+r_3 \\
-3r_2+r_4
\end{array} \rightarrow \left(\begin{array}{ccccccc} 0 & 0 & 27 & 0 & 9 & 0 & 0 & -18 \\ 0 & 0 & 0 & 27 & -7 & -3 & 9 & 26 \\ 0 & 27 & 0 & 0 & 1 & 12 & -9 & -23 \\ 27 & 0 & 0 & 0 & 12 & 9 & -27 & -33 \end{array} \right) \\
\begin{array}{c}
r_1 \leftrightarrow r_4 \\
r_2 \leftrightarrow r_3 \\
r_3 \leftrightarrow r_4
\end{array} \rightarrow \left(\begin{array}{ccccccc} 27 & 0 & 0 & 0 & 12 & 9 & -27 & -33 \\ 0 & 27 & 0 & 0 & 1 & 12 & -9 & -23 \\ 0 & 0 & 27 & 0 & 9 & 0 & 0 & -18 \\ 0 & 0 & 0 & 27 & -7 & -3 & 9 & 26 \end{array} \right)
\end{array}$$

所以有: $\mathbf{C} = \begin{pmatrix} 2 & 0 & 5 & 6 \\ 1 & 3 & 3 & 6 \\ -1 & 1 & 2 & 1 \\ 1 & 0 & 1 & 3 \end{pmatrix}^{-1} = \frac{1}{27} \begin{pmatrix} 12 & 9 & -27 & -33 \\ 1 & 12 & -9 & -23 \\ 9 & 0 & 0 & -18 \\ -7 & -3 & 9 & 26 \end{pmatrix}$.

设 $\xi = (x_1, x_2, x_3, x_4)^T$ 在 $\beta_1, \beta_2, \beta_3, \beta_4$ 下的坐标为 $(y_1, y_2, y_3, y_4)^T$, 则有:
 $(\alpha_1, \alpha_2, \alpha_3, \alpha_4)(x_1, x_2, x_3, x_4)^T = (\beta_1, \beta_2, \beta_3, \beta_4)(y_1, y_2, y_3, y_4)^T$,
 $(\beta_1, \beta_2, \beta_3, \beta_4)\mathbf{C}(x_1, x_2, x_3, x_4)^T = (\beta_1, \beta_2, \beta_3, \beta_4)(y_1, y_2, y_3, y_4)^T$,

$$(y_1, y_2, y_3, y_4)^T = \mathbf{C}(x_1, x_2, x_3, x_4)^T = \frac{1}{27} \begin{pmatrix} 12 & 9 & -27 & -33 \\ 1 & 12 & -9 & -23 \\ 9 & 0 & 0 & -18 \\ -7 & -3 & 9 & 26 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix}$$

要使在两个基下面有相同的坐标, 必须 $(y_1, y_2, y_3, y_4)^T = (x_1, x_2, x_3, x_4)^T$ 即:

$$\begin{array}{l}
\begin{array}{c}
\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \frac{1}{27} \begin{pmatrix} 12 & 9 & -27 & -33 \\ 1 & 12 & -9 & -23 \\ 9 & 0 & 0 & -18 \\ -7 & -3 & 9 & 26 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix}, \text{ 整理得: } \begin{pmatrix} -15 & 9 & -27 & -33 \\ 1 & -15 & -9 & -23 \\ 9 & 0 & -27 & -18 \\ -7 & -3 & 9 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = 0
\end{array} \\
\begin{array}{c}
\begin{pmatrix} -15 & 9 & -27 & -33 \\ 1 & -15 & -9 & -23 \\ 9 & 0 & -27 & -18 \\ -7 & -3 & 9 & -1 \end{pmatrix} \xrightarrow{\begin{array}{l} \frac{1}{3}r_1 \\ \frac{1}{9}r_3 \end{array}} \begin{pmatrix} -5 & 3 & -9 & -11 \\ 1 & -15 & -9 & -23 \\ 1 & 0 & -3 & -2 \\ -7 & -3 & 9 & -1 \end{pmatrix} \xrightarrow{\begin{array}{l} 5r_3+r_1 \\ -r_3+r_2 \\ 7r_3+r_4 \end{array}} \begin{pmatrix} 0 & 3 & -24 & -21 \\ 0 & -15 & -6 & -21 \\ 1 & 0 & -3 & -2 \\ 0 & -3 & -12 & -15 \end{pmatrix} \\
\begin{array}{c}
\begin{pmatrix} 0 & 3 & -24 & -21 \\ 0 & 0 & -126 & -126 \\ 1 & 0 & -3 & -2 \\ 0 & 0 & -36 & -36 \end{pmatrix} \xrightarrow{\begin{array}{l} \frac{1}{3}r_1 \\ -\frac{1}{126}r_2 \\ 36r_2+r_4 \end{array}} \begin{pmatrix} 0 & 1 & -8 & -7 \\ 0 & 0 & 1 & 1 \\ 1 & 0 & -3 & -2 \\ 0 & 0 & 0 & 0 \end{pmatrix} \xrightarrow{\begin{array}{l} 8r_2+r_1 \\ 3r_2+r_3 \end{array}} \begin{pmatrix} 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}
\end{array}
\end{array}
\end{array}$$

得基础解系 $\xi = (-1, -1, -1, 1)^T$ 即为所求非零向量, 在两组基下有相同的坐标.

8. 判别下面所定义的变换, 哪些是线性变换, 哪些不是?

(1) 在线性空间 V 中, $T(\xi) = \xi + \alpha$, 其中 $\alpha \in V$ 是一固定向量;

(2) 在 \mathbf{R}^3 中, $T(\alpha) = \alpha + (1, 0, 0)$, $\alpha \in \mathbf{R}^3$;

(3) 在 $\mathbf{R}^{n \times n}$ 中, $T(X) = BXC$, 其中 $B, C \in \mathbf{R}^{n \times n}$ 是两个固定矩阵.

解:

(1) 当 $\alpha=0$ 时, $T(\xi) = \xi$ 显然为线性变换中的恒等变换;

当 $\alpha \neq 0$ 时, $T(2\xi) - 2T(\xi) = (2\xi + \alpha) - 2(\xi + \alpha) = -\alpha \neq 0$, 所以 $T(2\xi) \neq 2T(\xi)$, 说明此时 $T(\xi) = \xi + \alpha$ 不是线性变换.

综上, 当且仅当 $\alpha=0$ 时, $T(\xi) = \xi + \alpha$ 是线性变换.

(2) 由(1)结论可知, $T(\alpha) = \alpha + (1, 0, 0)$, $\alpha \in \mathbf{R}^3$ 不是线性变换.

(3) 因为任取 $X, Y \in \mathbf{R}^{n \times n}$, $k \in \mathbf{R}$ 有:

$$T(X+Y) = B(X+Y)C = BXC + BYC = T(X) + T(Y)$$

$$T(kX) = B(kX)C = kBXC = kT(X)$$

所以 $T(X) = BX$ 是线性变换.

9. 在 n 维线性空间 $\mathbf{R}[x]_n$ 中, 定义线性变换微分运算 $\Gamma(f(x)) = f'(x)$, 其中 $f(x) \in \mathbf{R}[x]_n$. 求 Γ 的值域与核.

解:

任取 $f(x) = a_0 + a_1x + \dots + a_nx^n \in \mathbf{R}[x]_n$, 必然有: $\Gamma(f(x)) = f'(x) = a_1 + 2a_2x + \dots + na_nx^{n-1} \in \mathbf{R}[x]_{n-1}$

反之, 任取 $g(x) = b_0 + b_1x + \dots + b_{n-1}x^{n-1} \in \mathbf{R}[x]_{n-1}$, 有:

$$f(x) = b_0x + \frac{1}{2}b_1x^2 + \dots + \frac{1}{n}b_{n-1}x^n \in \mathbf{R}[x]_n \text{ 使得 } \Gamma(f(x)) = f'(x) = g(x)$$

所以 Γ 的值域为 $\mathbf{R}[x]_{n-1}$.

由高等数学知识易得 Γ 的核为 R .

10. 已知 \mathbf{R}^3 中, $\eta_1 = (-1, 0, 2)^T$, $\eta_2 = (0, 1, 1)^T$, $\eta_3 = (3, -1, 0)^T$, 定义线性变换 T 为

$$\begin{cases} T(\eta_1) = (-5, 0, 3)^T, \\ T(\eta_2) = (0, -1, 6)^T, \\ T(\eta_3) = (-5, -1, 9)^T, \end{cases}$$

求 T 在基 $\epsilon_1 = (1, 0, 0)^T$, $\epsilon_2 = (0, 1, 0)^T$, $\epsilon_3 = (0, 0, 1)^T$ 下的矩阵.

解:

$$\text{因为 } (\eta_1, \eta_2, \eta_3) = (\epsilon_1, \epsilon_2, \epsilon_3) \begin{pmatrix} -1 & 0 & 3 \\ 0 & 1 & -1 \\ 2 & 1 & 0 \end{pmatrix},$$

所以有:

$$\begin{aligned} (\epsilon_1, \epsilon_2, \epsilon_3) &= (\eta_1, \eta_2, \eta_3) \begin{pmatrix} -1 & 0 & 3 \\ 0 & 1 & -1 \\ 2 & 1 & 0 \end{pmatrix}^{-1} \\ &\left(\begin{array}{cccccc} -1 & 0 & 3 & 1 & 0 & 0 \\ 0 & 1 & -1 & 0 & 1 & 0 \\ 2 & 1 & 0 & 0 & 0 & 1 \end{array} \right) \xrightarrow{2r_1+r_3} \left(\begin{array}{cccccc} -1 & 0 & 3 & 1 & 0 & 0 \\ 0 & 1 & -1 & 0 & 1 & 0 \\ 0 & 1 & 6 & 2 & 0 & 1 \end{array} \right) \xrightarrow{-r_2+r_3} \left(\begin{array}{cccccc} -1 & 0 & 3 & 1 & 0 & 0 \\ 0 & 1 & -1 & 0 & 1 & 0 \\ 0 & 0 & 7 & 2 & -1 & 1 \end{array} \right) \\ &\xrightarrow[7r_2]{-7r_1} \left(\begin{array}{cccccc} 7 & 0 & -21 & -7 & 0 & 0 \\ 0 & 7 & -7 & 0 & 7 & 0 \\ 0 & 0 & 7 & 2 & -1 & 1 \end{array} \right) \xrightarrow[r_3+r_2]{3r_3+r_1} \left(\begin{array}{cccccc} 7 & 0 & 0 & -1 & -3 & 3 \\ 0 & 7 & 0 & 2 & 6 & 1 \\ 0 & 0 & 7 & 2 & -1 & 1 \end{array} \right) \end{aligned}$$

$$\begin{aligned}
(\boldsymbol{\varepsilon}_1, \boldsymbol{\varepsilon}_2, \boldsymbol{\varepsilon}_3) &= (\boldsymbol{\eta}_1, \boldsymbol{\eta}_2, \boldsymbol{\eta}_3) \frac{1}{7} \begin{pmatrix} -1 & -3 & 3 \\ 2 & 6 & 1 \\ 2 & -1 & 1 \end{pmatrix} = \frac{1}{7} (-\boldsymbol{\eta}_1 + 2\boldsymbol{\eta}_2 + 2\boldsymbol{\eta}_3, -3\boldsymbol{\eta}_1 + 6\boldsymbol{\eta}_2 - \boldsymbol{\eta}_3, 3\boldsymbol{\eta}_1 + \\
\boldsymbol{\eta}_2 + \boldsymbol{\eta}_3) \\
\mathbf{T}(\boldsymbol{\varepsilon}_1) &= \frac{1}{7} (-\mathbf{T}(\boldsymbol{\eta}_1) + 2\mathbf{T}(\boldsymbol{\eta}_2) + 2\mathbf{T}(\boldsymbol{\eta}_3)) = \frac{1}{7} \left(-\begin{pmatrix} -5 \\ 0 \\ 3 \end{pmatrix} + 2 \begin{pmatrix} 0 \\ 1 \\ 6 \end{pmatrix} + 2 \begin{pmatrix} -5 \\ -1 \\ 9 \end{pmatrix} \right) = \frac{1}{7} \begin{pmatrix} -5 \\ 0 \\ 27 \end{pmatrix} \\
\mathbf{T}(\boldsymbol{\varepsilon}_2) &= \frac{1}{7} (-3\mathbf{T}(\boldsymbol{\eta}_1) + 6\mathbf{T}(\boldsymbol{\eta}_2) - \mathbf{T}(\boldsymbol{\eta}_3)) = \frac{1}{7} \left(-3 \begin{pmatrix} -5 \\ 0 \\ 3 \end{pmatrix} + 6 \begin{pmatrix} 0 \\ 1 \\ 6 \end{pmatrix} - \begin{pmatrix} -5 \\ -1 \\ 9 \end{pmatrix} \right) = \frac{1}{7} \begin{pmatrix} 20 \\ 7 \\ 9 \end{pmatrix} \\
\mathbf{T}(\boldsymbol{\varepsilon}_3) &= \frac{1}{7} (3\mathbf{T}(\boldsymbol{\eta}_1) + \mathbf{T}(\boldsymbol{\eta}_2) + \mathbf{T}(\boldsymbol{\eta}_3)) = \frac{1}{7} \left(3 \begin{pmatrix} -5 \\ 0 \\ 3 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \\ 6 \end{pmatrix} + \begin{pmatrix} -5 \\ -1 \\ 9 \end{pmatrix} \right) = \frac{1}{7} \begin{pmatrix} -20 \\ 0 \\ 24 \end{pmatrix} \\
\text{因此 } \mathbf{T}(\boldsymbol{\varepsilon}_1, \boldsymbol{\varepsilon}_2, \boldsymbol{\varepsilon}_3) &= (\mathbf{T}(\boldsymbol{\varepsilon}_1), \mathbf{T}(\boldsymbol{\varepsilon}_2), \mathbf{T}(\boldsymbol{\varepsilon}_3)) = (\boldsymbol{\varepsilon}_1, \boldsymbol{\varepsilon}_2, \boldsymbol{\varepsilon}_3) \frac{1}{7} \begin{pmatrix} -5 & 20 & -20 \\ 0 & 7 & 0 \\ 27 & 9 & 24 \end{pmatrix},
\end{aligned}$$

所以 \mathbf{T} 在基 $\boldsymbol{\varepsilon}_1 = (1, 0, 0)^T$, $\boldsymbol{\varepsilon}_2 = (0, 1, 0)^T$, $\boldsymbol{\varepsilon}_3 = (0, 0, 1)^T$ 下的矩阵为:

$$\frac{1}{7} \begin{pmatrix} -5 & 20 & -20 \\ 0 & 7 & 0 \\ 27 & 9 & 24 \end{pmatrix}.$$

11. 给定线性空间 \mathbf{R}^3 中的两组基

$$\boldsymbol{\varepsilon}_1 = (1, 0, 1)^T, \boldsymbol{\varepsilon}_2 = (2, 1, 0)^T, \boldsymbol{\varepsilon}_3 = (1, 1, 1)^T$$

$$\boldsymbol{\eta}_1 = (1, 2, -1)^T, \boldsymbol{\eta}_2 = (2, 2, -1)^T, \boldsymbol{\eta}_3 = (2, -1, -1)^T$$

求从基 $\boldsymbol{\varepsilon}_1, \boldsymbol{\varepsilon}_2, \boldsymbol{\varepsilon}_3$ 到基 $\boldsymbol{\eta}_1, \boldsymbol{\eta}_2, \boldsymbol{\eta}_3$ 的过渡矩阵.

解:

设从基 $\boldsymbol{\varepsilon}_1, \boldsymbol{\varepsilon}_2, \boldsymbol{\varepsilon}_3$ 到基 $\boldsymbol{\eta}_1, \boldsymbol{\eta}_2, \boldsymbol{\eta}_3$ 的过渡矩阵为 C , 则 $(\boldsymbol{\eta}_1, \boldsymbol{\eta}_2, \boldsymbol{\eta}_3) = (\boldsymbol{\varepsilon}_1, \boldsymbol{\varepsilon}_2, \boldsymbol{\varepsilon}_3)C$, 于是:

$$\begin{aligned}
C &= (\boldsymbol{\varepsilon}_1, \boldsymbol{\varepsilon}_2, \boldsymbol{\varepsilon}_3)^{-1} (\boldsymbol{\eta}_1, \boldsymbol{\eta}_2, \boldsymbol{\eta}_3) = \begin{pmatrix} 1 & 2 & 1 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{pmatrix}^{-1} \begin{pmatrix} 1 & 2 & 2 \\ 2 & 2 & -1 \\ -1 & -1 & -1 \end{pmatrix} \\
&\begin{pmatrix} 1 & 2 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 0 & 1 \end{pmatrix} \xrightarrow[-r_3+r_1]{-r_2} \begin{pmatrix} 0 & 2 & 0 & 1 & 0 & -1 \\ 0 & 2 & 2 & 0 & 2 & 0 \\ 1 & 0 & 1 & 0 & 0 & 1 \end{pmatrix} \xrightarrow[-r_1+r_2]{-2r_3} \begin{pmatrix} 0 & 2 & 0 & 1 & 0 & -1 \\ 0 & 0 & 2 & -1 & 2 & 1 \\ 2 & 0 & 2 & 0 & 0 & 2 \end{pmatrix} \\
&\xrightarrow[-r_2+r_3]{-r_2+r_3} \begin{pmatrix} 0 & 2 & 0 & 1 & 0 & -1 \\ 0 & 0 & 2 & -1 & 2 & 1 \\ 2 & 0 & 0 & 1 & -2 & 1 \end{pmatrix} \xrightarrow[r_1 \leftrightarrow r_3]{r_2 \leftrightarrow r_3} \begin{pmatrix} 2 & 0 & 0 & 1 & -2 & 1 \\ 0 & 2 & 0 & 1 & 0 & -1 \\ 0 & 0 & 2 & -1 & 2 & 1 \end{pmatrix}
\end{aligned}$$

于是我们得到, 从基 $\boldsymbol{\varepsilon}_1, \boldsymbol{\varepsilon}_2, \boldsymbol{\varepsilon}_3$ 到基 $\boldsymbol{\eta}_1, \boldsymbol{\eta}_2, \boldsymbol{\eta}_3$ 的过渡矩阵:

$$C = \frac{1}{2} \begin{pmatrix} 1 & -2 & 1 \\ 1 & 0 & -1 \\ -1 & 2 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 & 2 \\ 2 & 2 & -1 \\ -1 & -1 & -1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} -4 & -3 & 3 \\ 2 & 3 & 3 \\ 2 & 1 & -5 \end{pmatrix}$$